

CS208: Applied Privacy for Data Science

Introduction to Differential Privacy

School of Engineering & Applied Sciences
Harvard University

February 8, 2022

Attacks on Aggregate Stats

For releasing d population proportions on a dataset of size n :



Questions:

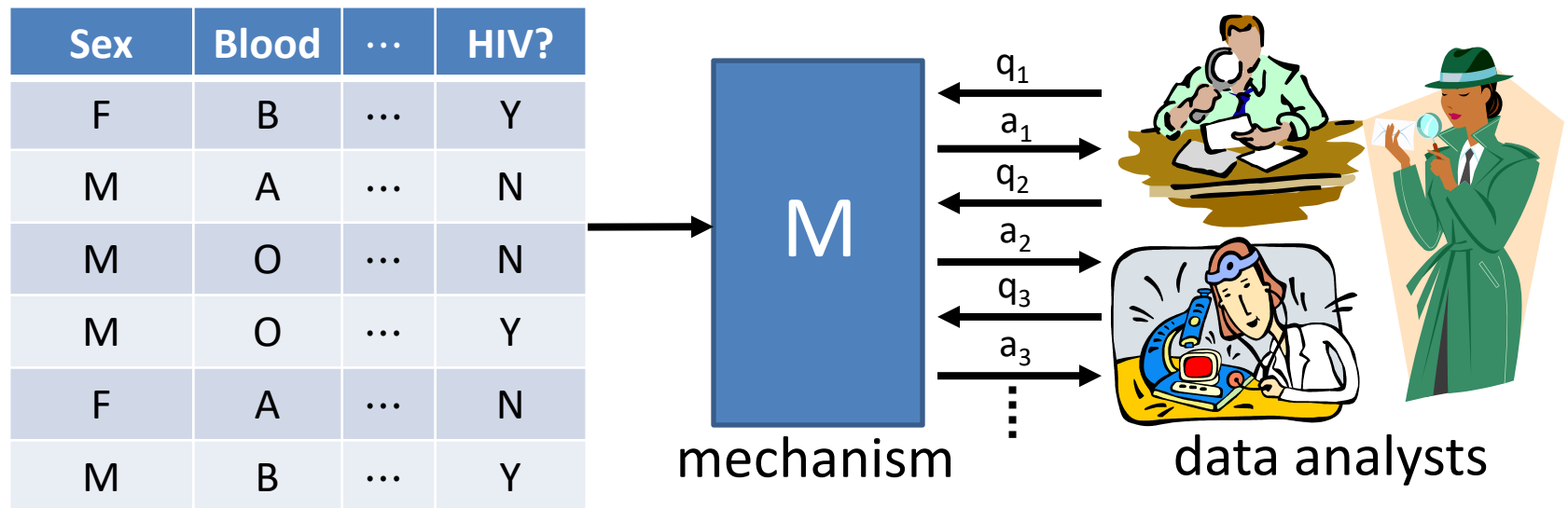
- If we allow error greater than \sqrt{d}/n , can we prevent these attacks?
- Can we reason about unforeseen attacks?

Goals of Differential Privacy

- **Utility:** enable “statistical analysis” of datasets
 - e.g. inference about population, ML training, useful descriptive statistics
- **Privacy:** protect individual-level data
 - against “all” attack strategies, auxiliary info.

Differential privacy

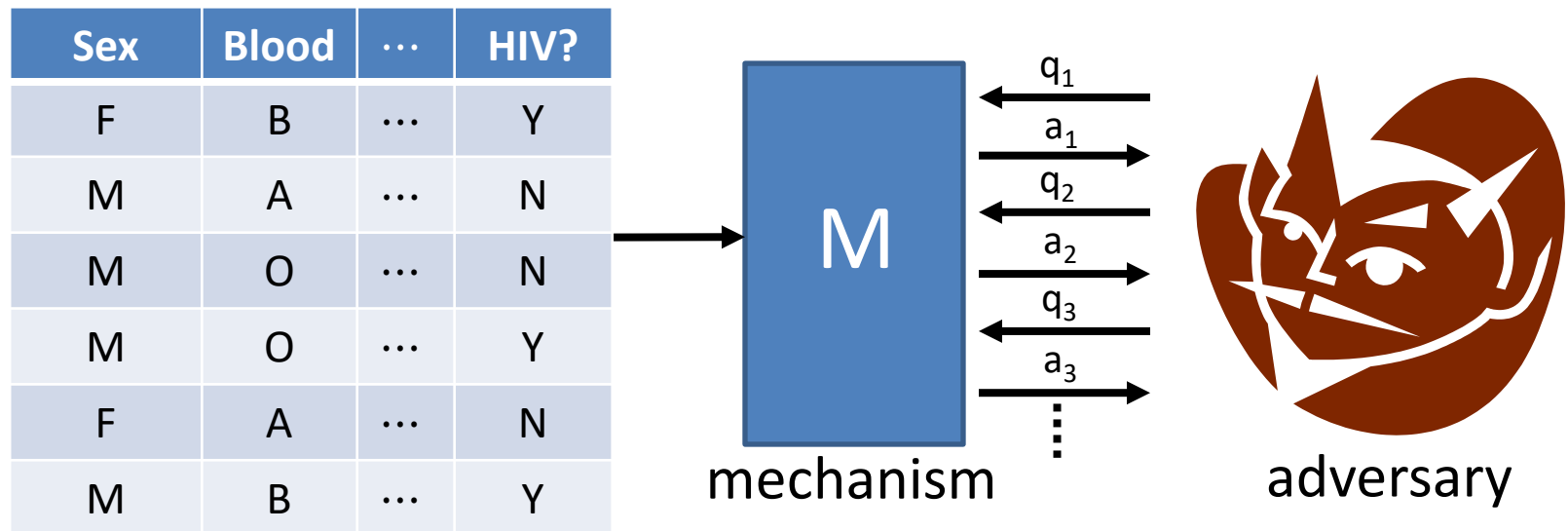
[Dinur-Nissim '03+Dwork, Dwork-Nissim '04, Blum-Dwork-McSherry-Nissim '05, Dwork-McSherry-Nissim-Smith '06]



Requirement: effect of each individual should be “hidden”

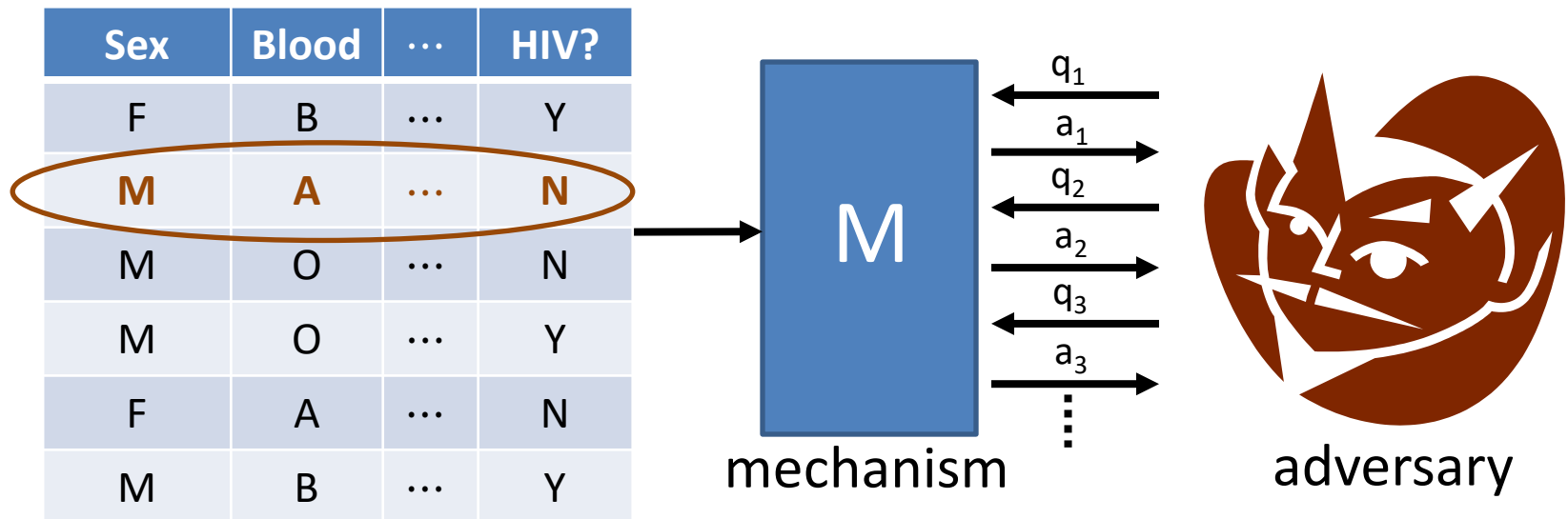
Differential privacy

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Differential privacy

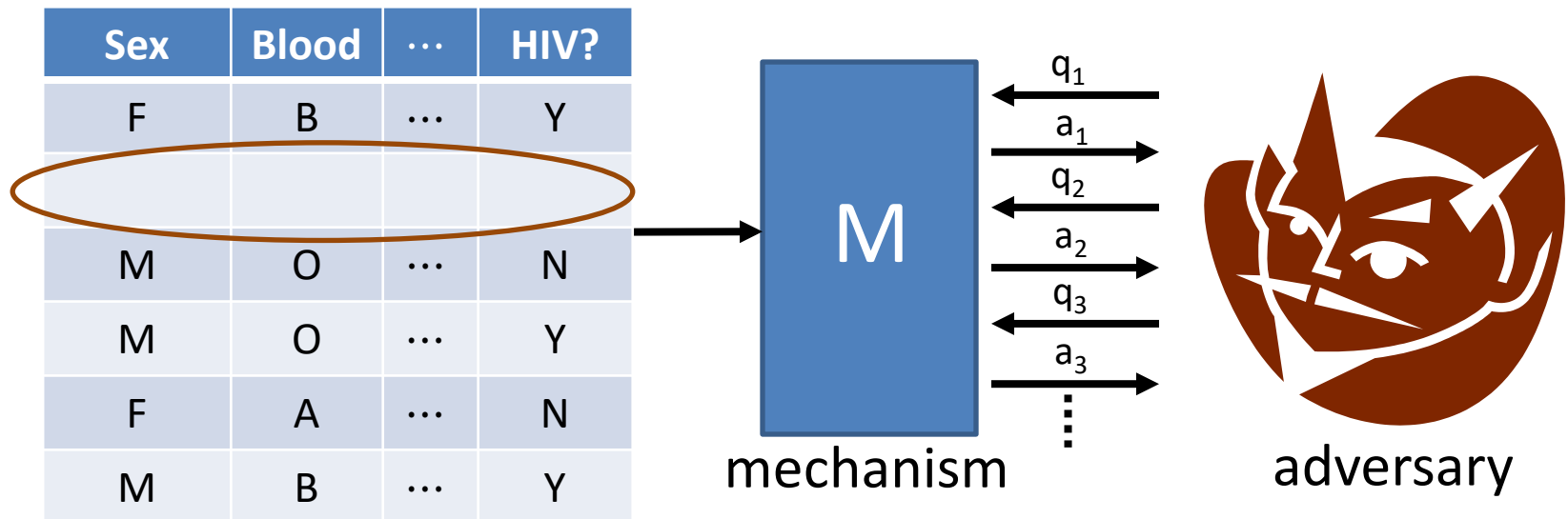
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Requirement: an adversary shouldn't be able to tell if any one person's data were changed arbitrarily

Differential privacy

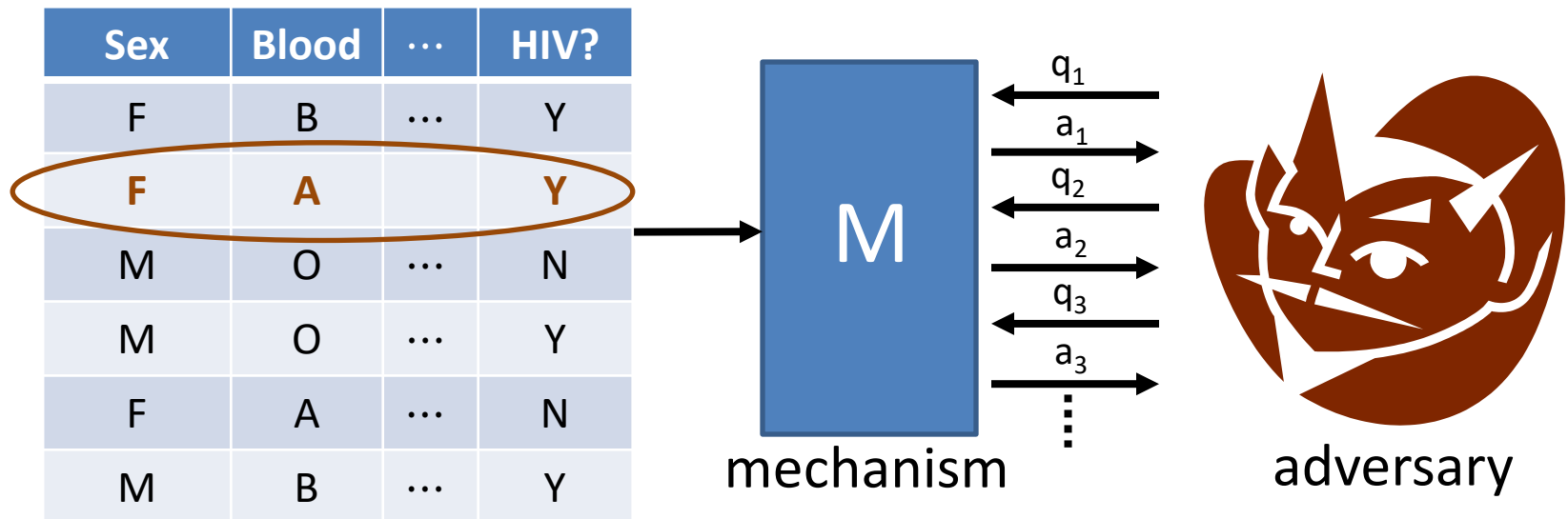
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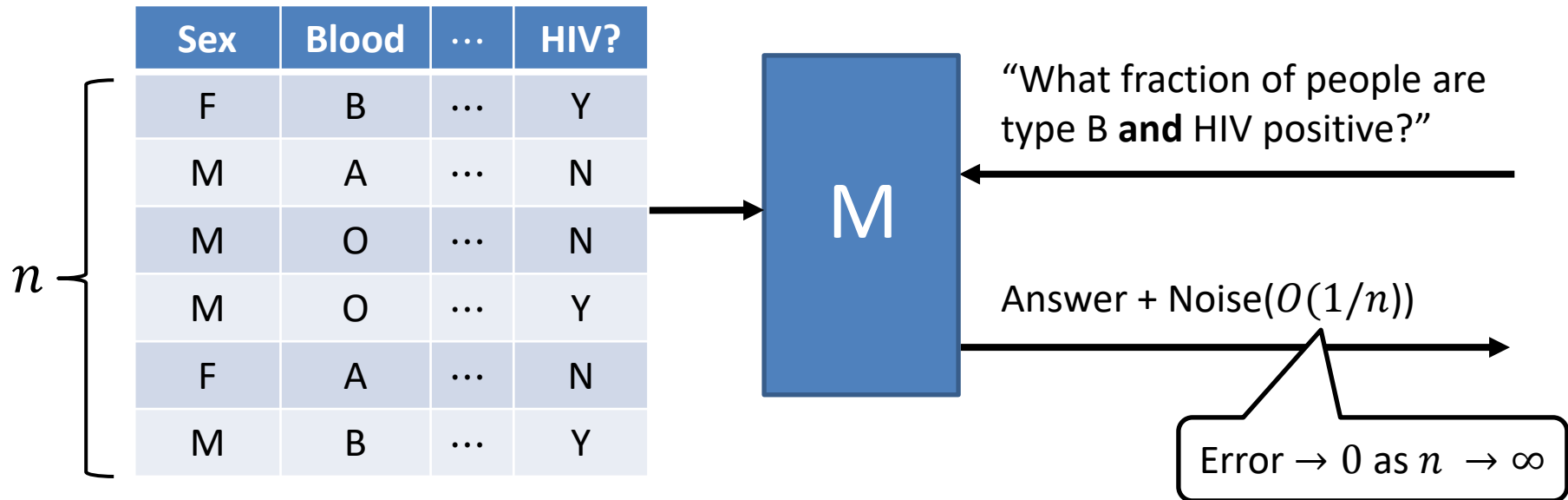
Differential privacy

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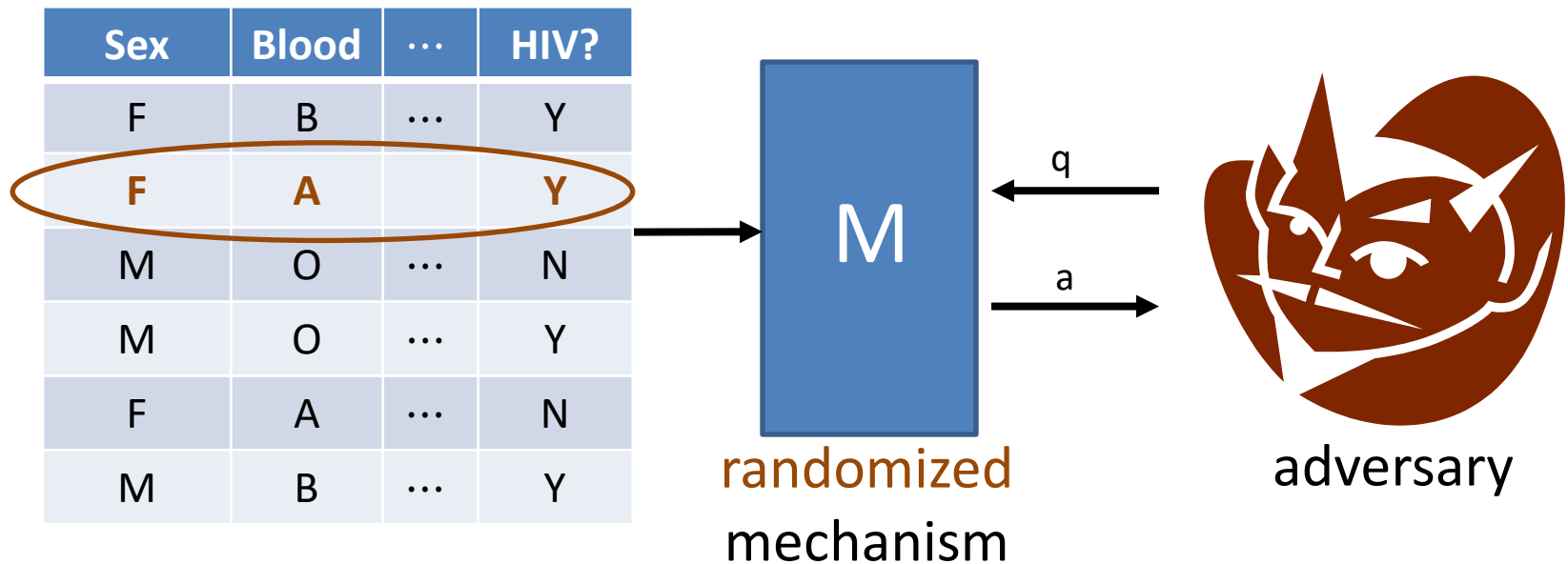
Simple approach: random noise



- Very little noise needed to hide each person as $n \rightarrow \infty$.
- **Note:** this is just for one query

DP for one query/release

[Dinur-Nissim '03+Dwork, Dwork-Nissim '04, Blum-Dwork-McSherry-Nissim '05, Dwork-McSherry-Nissim-Smith '06]

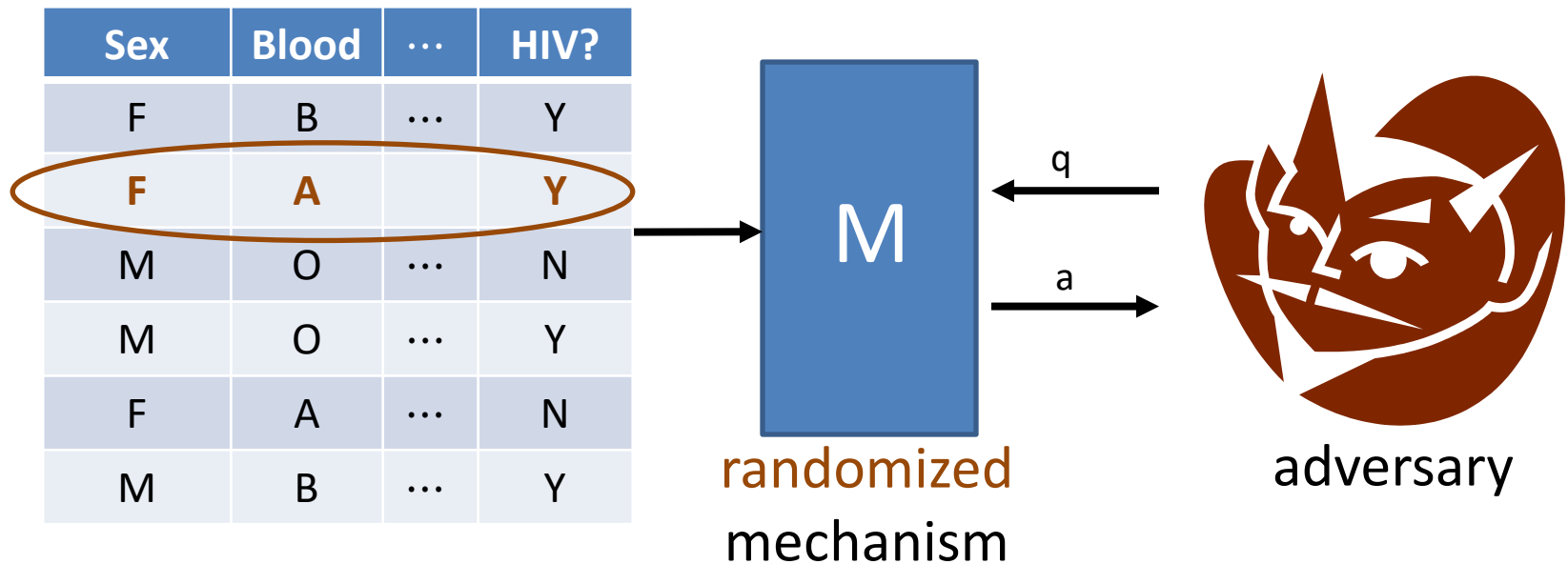


Requirement: for all x, x' differing on one row, and all q

Distribution of $M(x, q) \approx_{\epsilon}$ Distribution of $M(x', q)$

DP for one query/release

[Dinur-Nissim '03+Dwork, Dwork-Nissim '04, Blum-Dwork-McSherry-Nissim '05, Dwork-McSherry-Nissim-Smith '06]

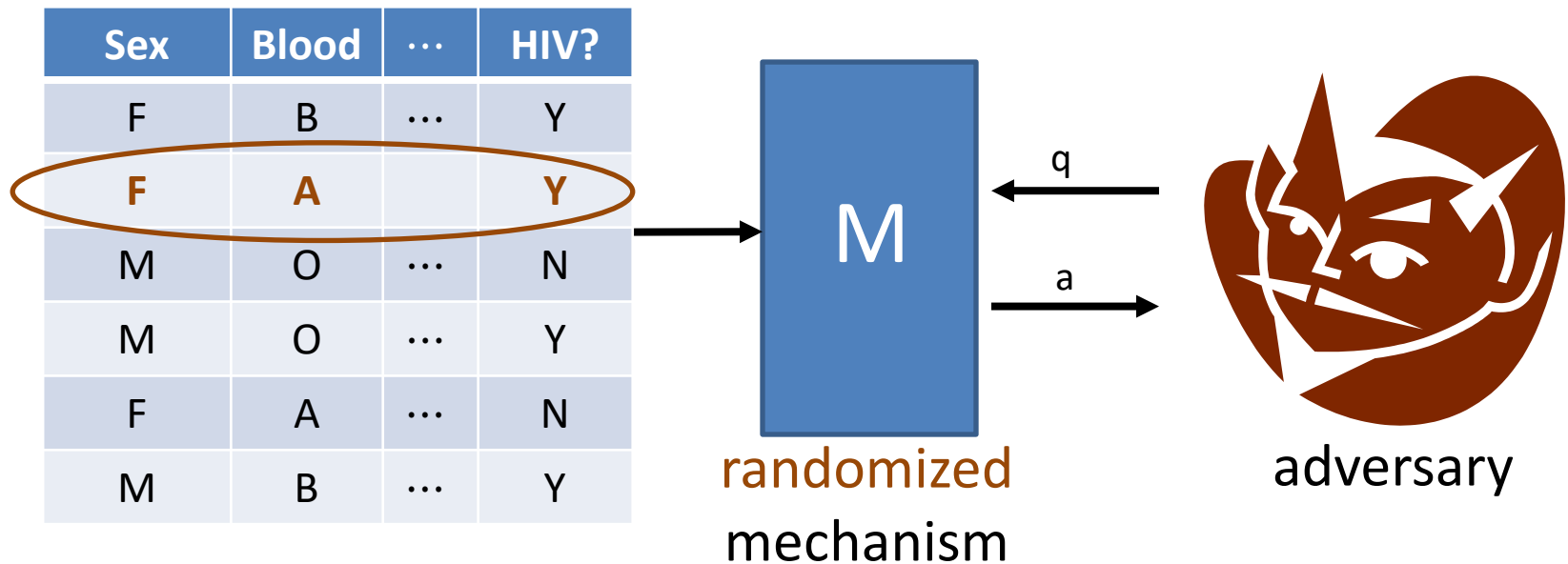


Requirement: for all x, x' differing on one row, and all q

$$\forall \text{ sets } T, \quad \Pr[M(x, q) \in T] \lesssim (1+\varepsilon) \cdot \Pr[M(x', q) \in T]$$

DP for one query/release

[Dwork-McSherry-Nissim-Smith '06]



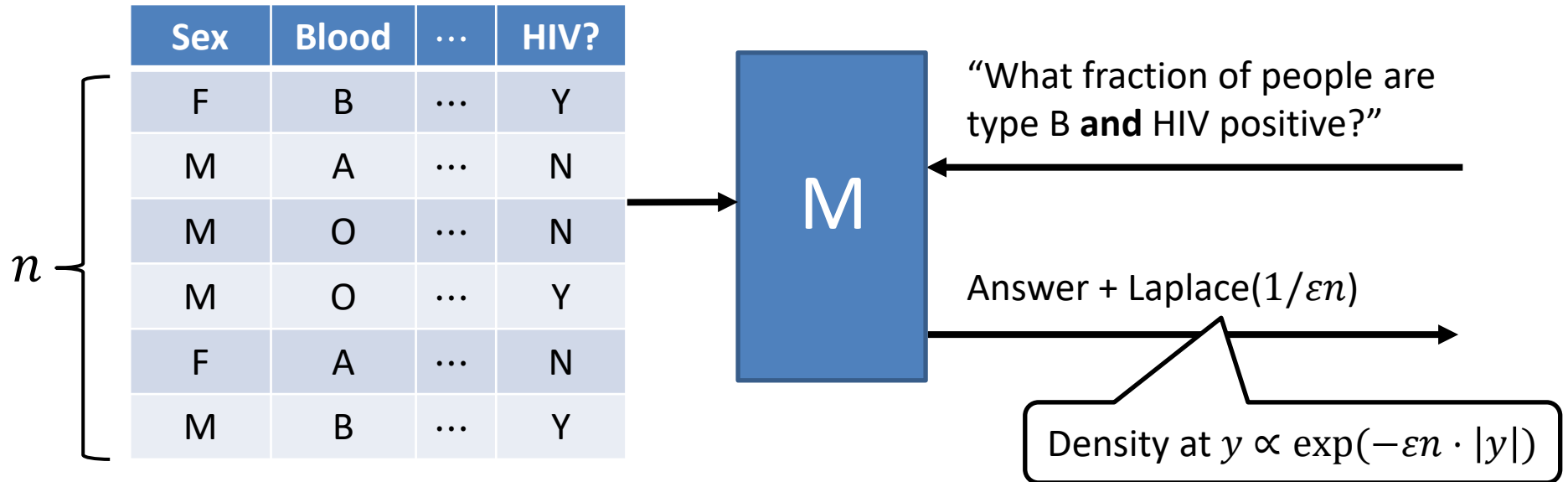
Def: M is ϵ -DP if for all x, x' differing on one row, and all q

$$\forall \text{ sets } T, \quad \Pr[M(x, q) \in T] \leq e^\epsilon \cdot \Pr[M(x', q) \in T]$$

(Probabilities are (only) over the randomness of M.)

The Laplace Mechanism

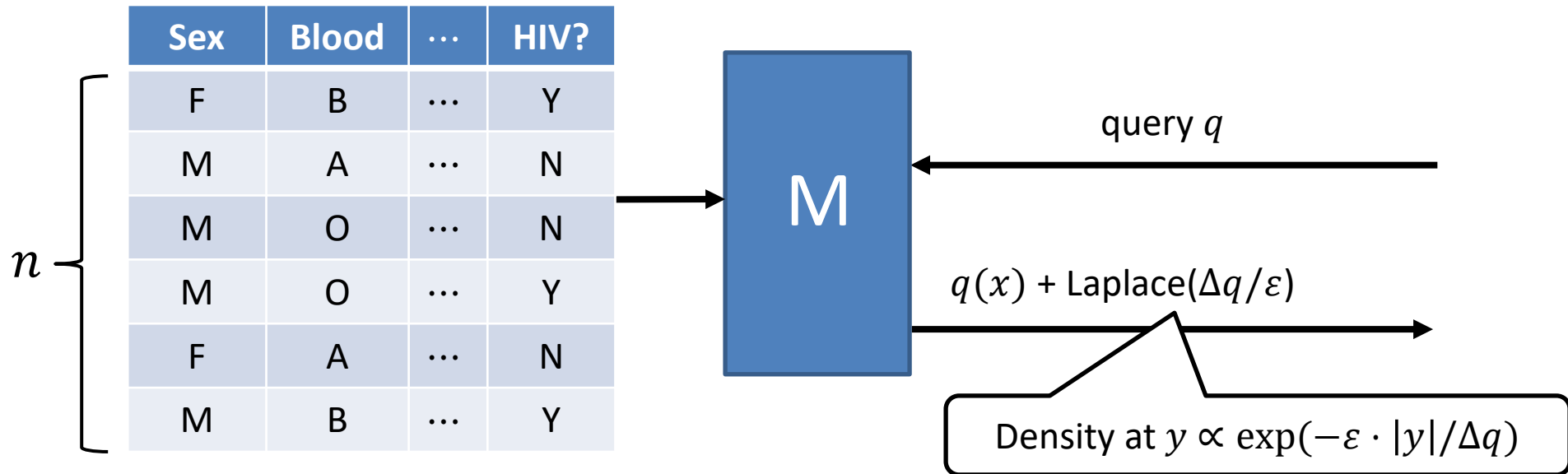
[Dwork-McSherry-Nissim-Smith '06]



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The Laplace Mechanism

[Dwork-McSherry-Nissim-Smith '06]



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The Laplace Mechanism

[Dwork-McSherry-Nissim-Smith '06]

- Let \mathcal{X} be a data universe, and \mathcal{X}^n a space of datasets.
 - This is the **Bounded DP** setting: n known and public.
- For $x, x' \in \mathcal{X}^n$, write $x \sim x'$ if x and x' differ on ≤ 1 row.

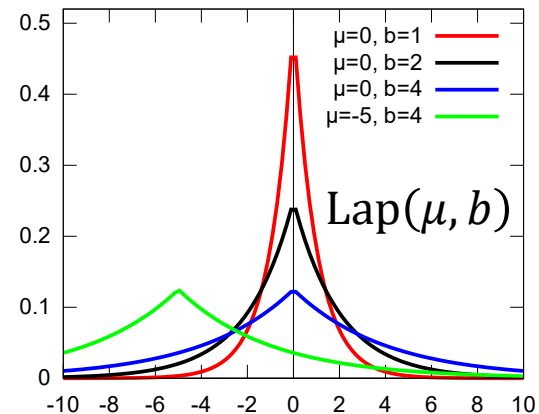
- For a query $q : \mathcal{X}^n \rightarrow \mathbb{R}$, the **global sensitivity** is

$$\Delta q = \text{GS}_q = \max_{x \sim x'} |q(x) - q(x')|.$$

- The **Laplace distribution** with scale s , $\text{Lap}(s)$:

- Has density function $f(y) = e^{-|y|/s} / 2s$.

- Mean 0, standard deviation $\sqrt{2} \cdot s$.



Theorem: $M(x, q) = q(x) + \text{Lap}(\Delta q/\epsilon)$ is ϵ -DP.

[By IkamusumeFan - Own work, CC BY-SA 4.0](#)

Calculating Global Sensitivity

1. $\mathcal{X} = \{0,1\}$, $q(x) = \sum_{i=1}^n x_i$, $\Delta q =$

2. $\mathcal{X} = \mathbb{R}$, $q(x) = \sum_{i=1}^n x_i$, $\Delta q =$

3. $\mathcal{X} = [0,1]$, $q(x) = \text{mean}(x_1, x_2, \dots, x_n)$, $\Delta q =$

4. $\mathcal{X} = [0,1]$, $q(x) = \text{median}(x_1, x_2, \dots, x_n)$, $\Delta q =$

5. $\mathcal{X} = [0,1]$, $q(x) = \text{variance}(x_1, x_2, \dots, x_n)$, $\Delta q =$

Q: for which of these queries is the Laplace Mechanism “useful”?

A: