

CS208: Applied Privacy for Data Science

Introduction to Differential Privacy

School of Engineering & Applied Sciences
Harvard University

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Attacks on Aggregate Stats

For releasing d population proportions on a dataset of size n :

Reconstruction attacks $d \geq n$

$$\frac{1}{\sqrt{n}}$$

Membership attacks

$$\frac{\sqrt{d}}{n}$$

Error α



Questions:

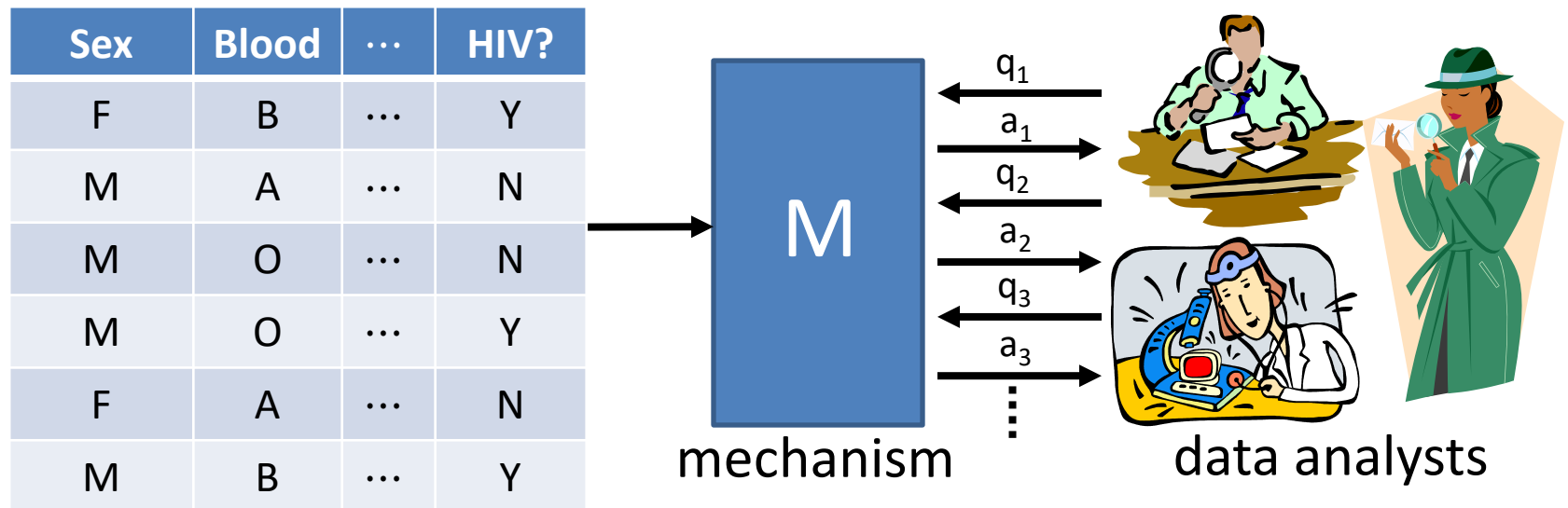
- If we allow error greater than \sqrt{d}/n , can we prevent these attacks?
- Can we reason about unforeseen attacks?

Goals of Differential Privacy

- **Utility:** enable “statistical analysis” of datasets
 - e.g. inference about population, ML training, useful descriptive statistics
- **Privacy:** protect individual-level data
 - against “all” attack strategies, auxiliary info.

Differential privacy

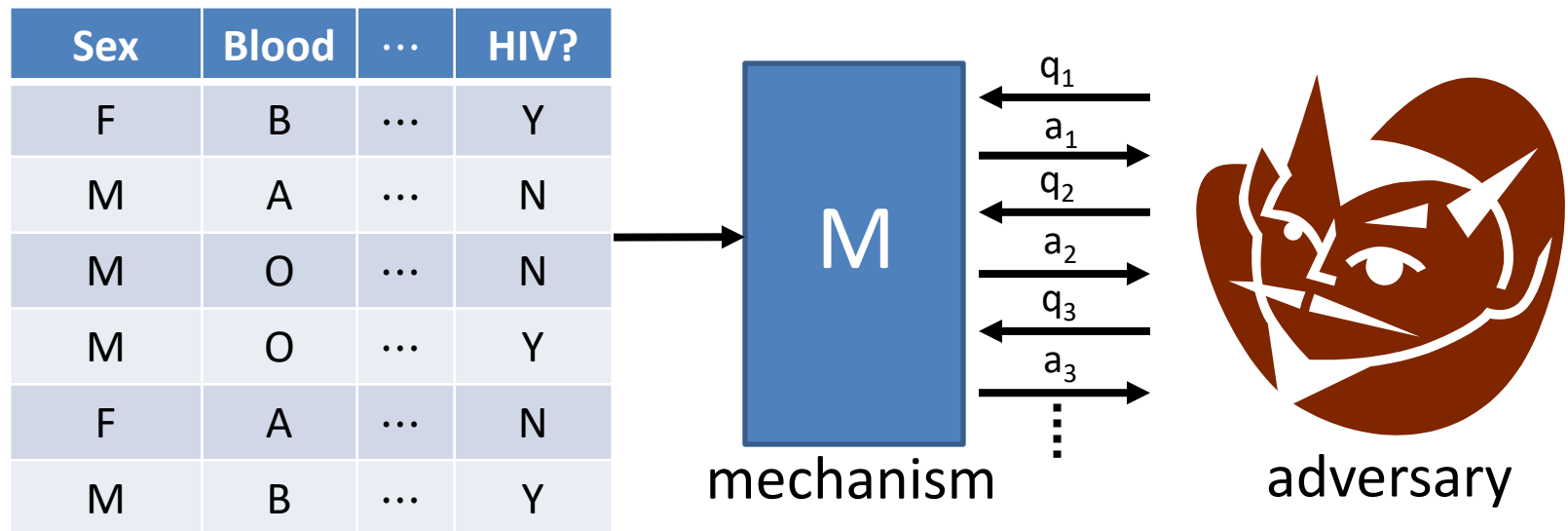
[Dinur-Nissim '03+Dwork, Dwork-Nissim '04, Blum-Dwork-McSherry-Nissim '05, Dwork-McSherry-Nissim-Smith '06]



Requirement: effect of each individual should be “hidden”

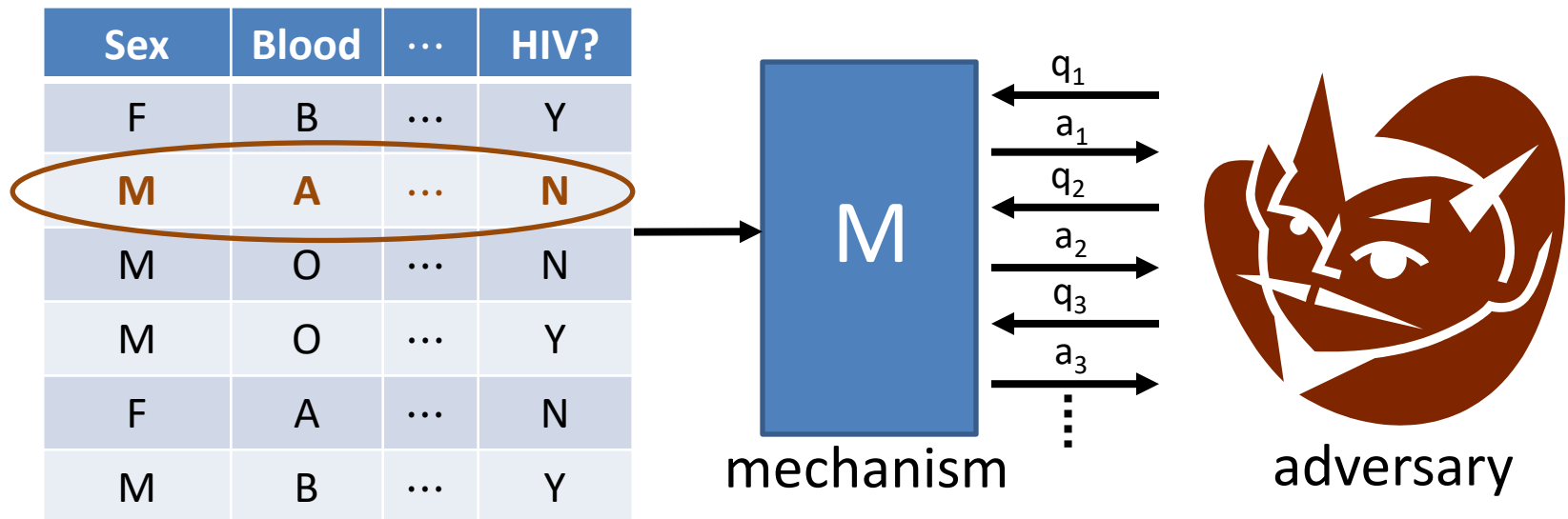
Differential privacy

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Differential privacy

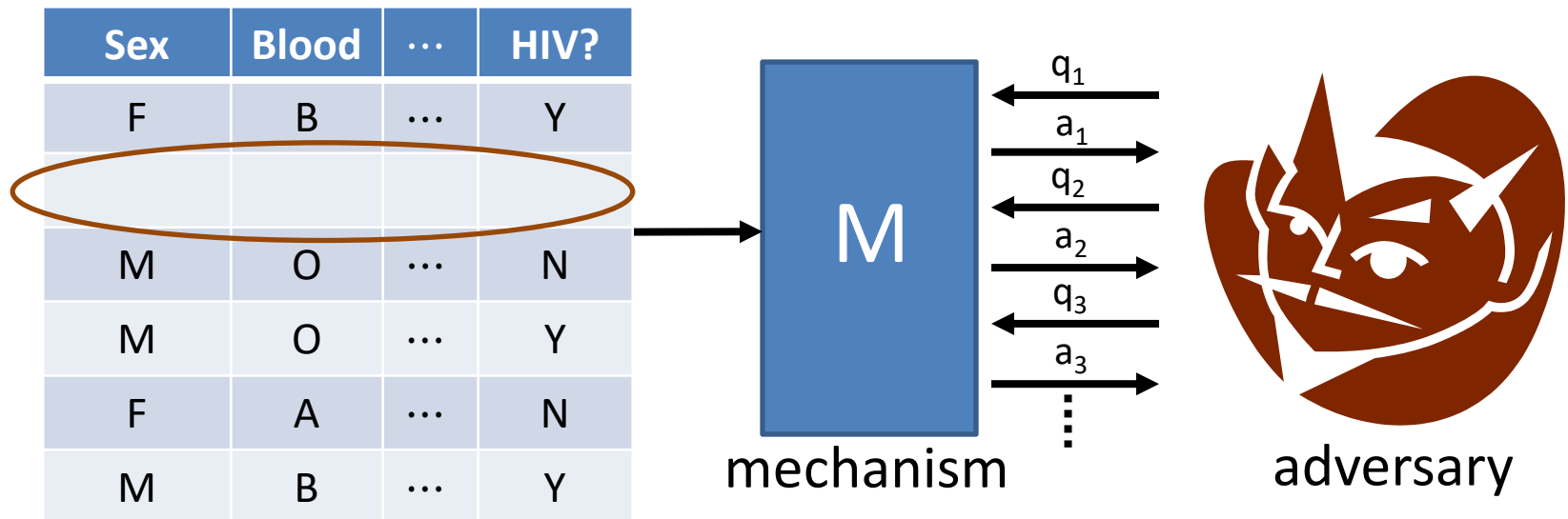
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Requirement: an adversary shouldn't be able to tell if any one person's data were changed arbitrarily

Differential privacy

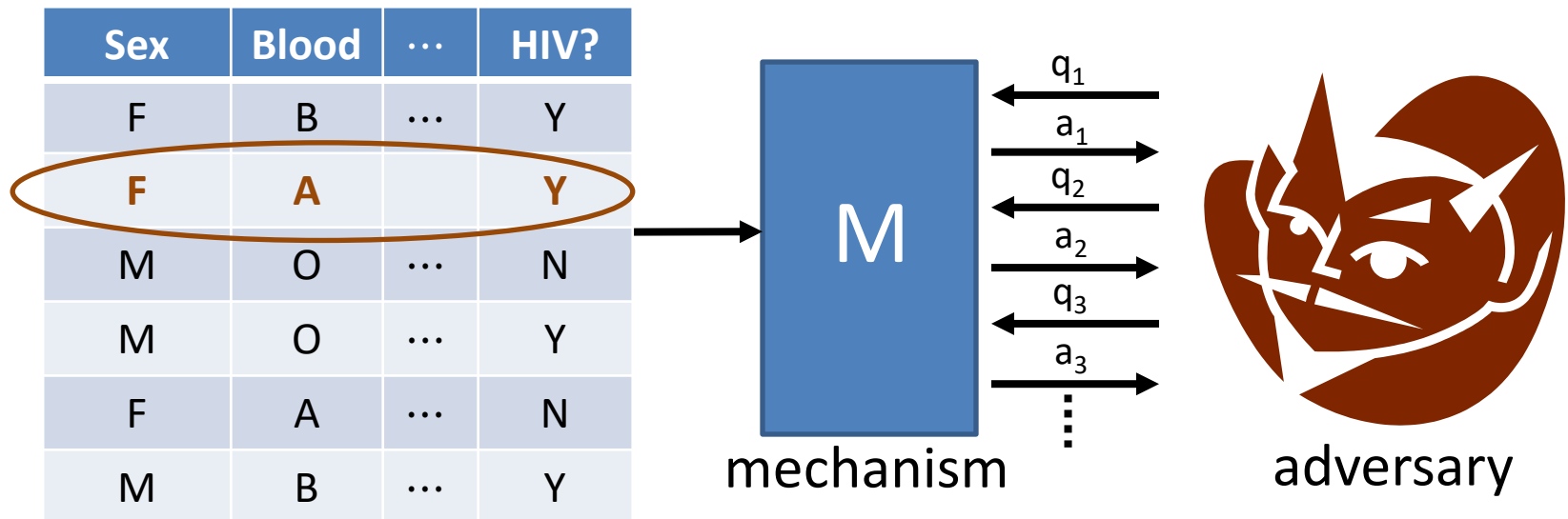
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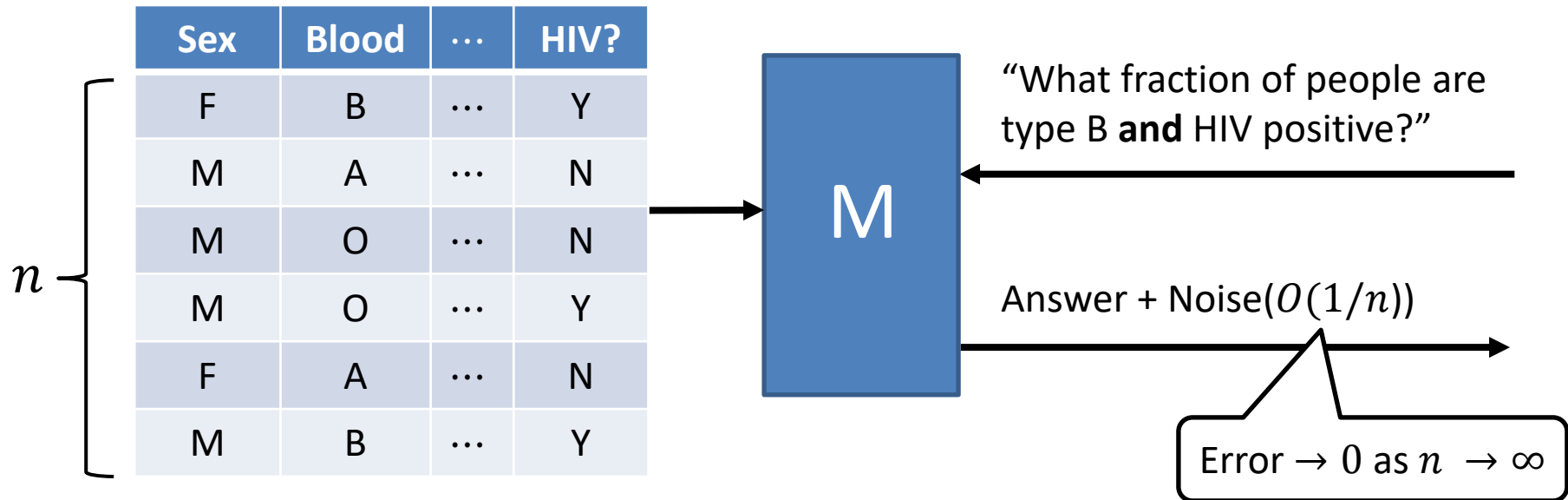
Differential privacy

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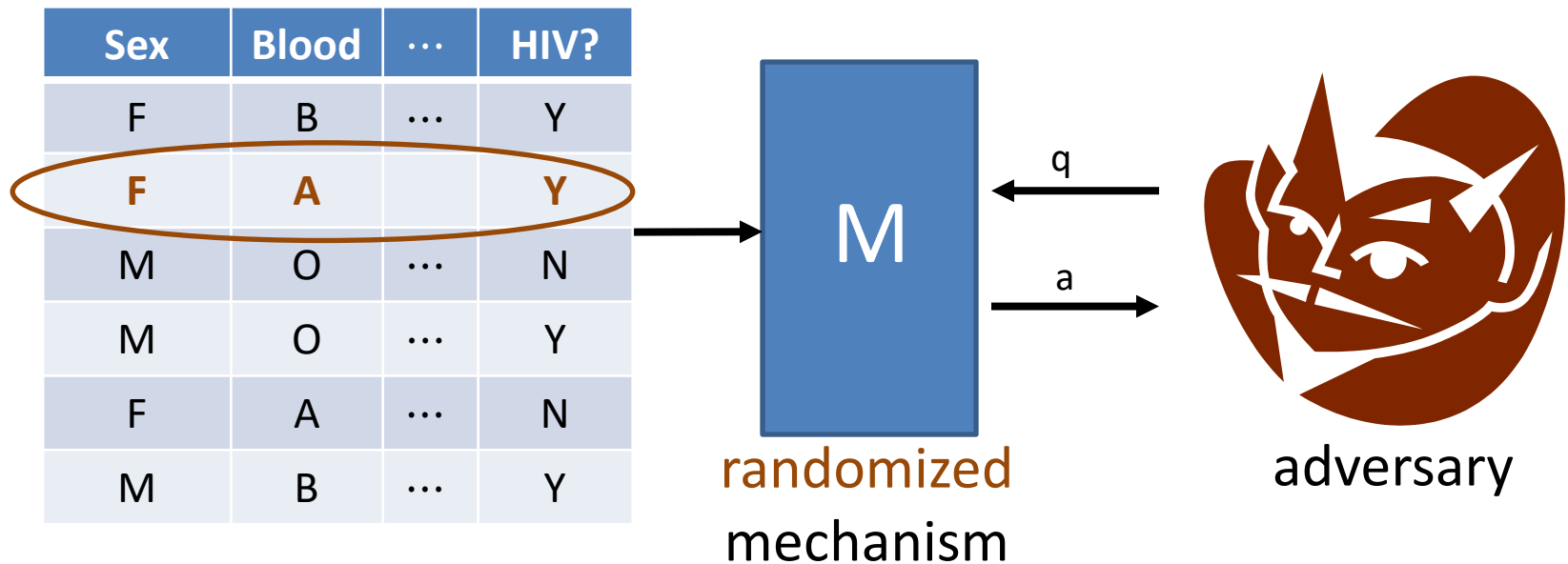
Simple approach: random noise



- Very little noise needed to hide each person as $n \rightarrow \infty$.
- **Note:** this is just for one query

DP for one query/release

[Dinur-Nissim '03+Dwork, Dwork-Nissim '04, Blum-Dwork-McSherry-Nissim '05, Dwork-McSherry-Nissim-Smith '06]

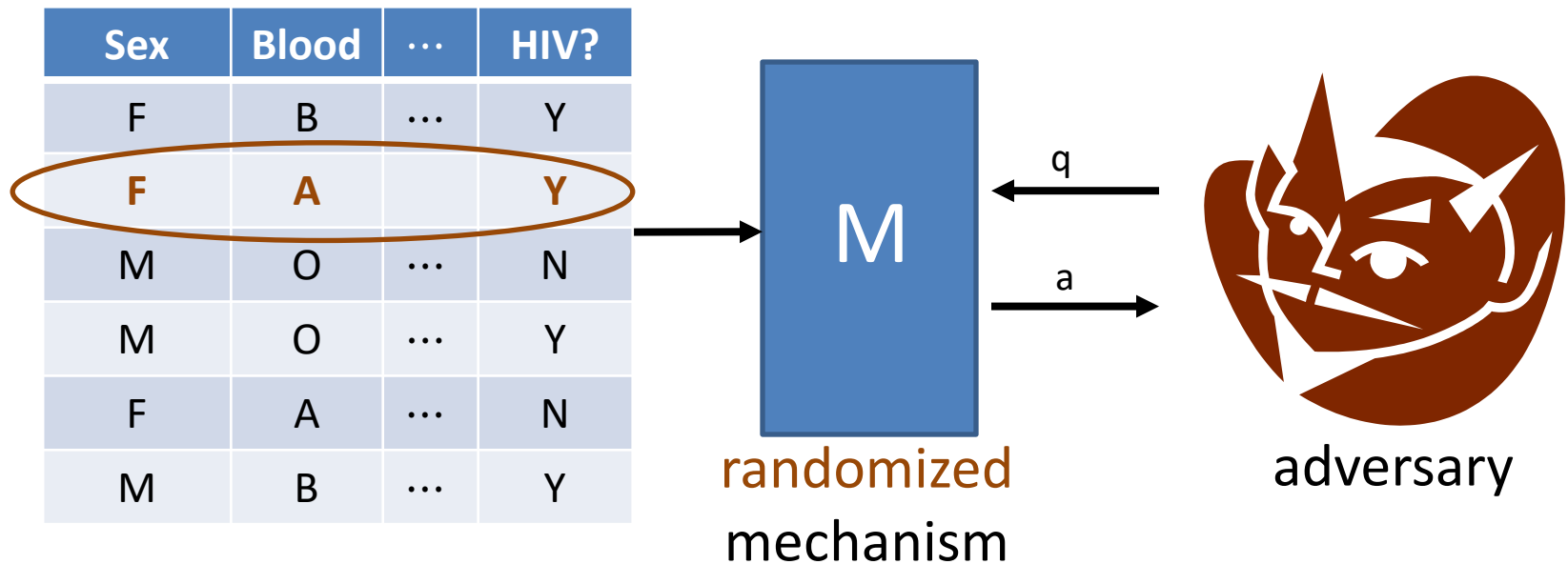


Requirement: for all x, x' differing on one row, and all q

Distribution of $M(x, q) \approx_{\epsilon}$ Distribution of $M(x', q)$

DP for one query/release

[Dinur-Nissim '03+Dwork, Dwork-Nissim '04, Blum-Dwork-McSherry-Nissim '05, Dwork-McSherry-Nissim-Smith '06]

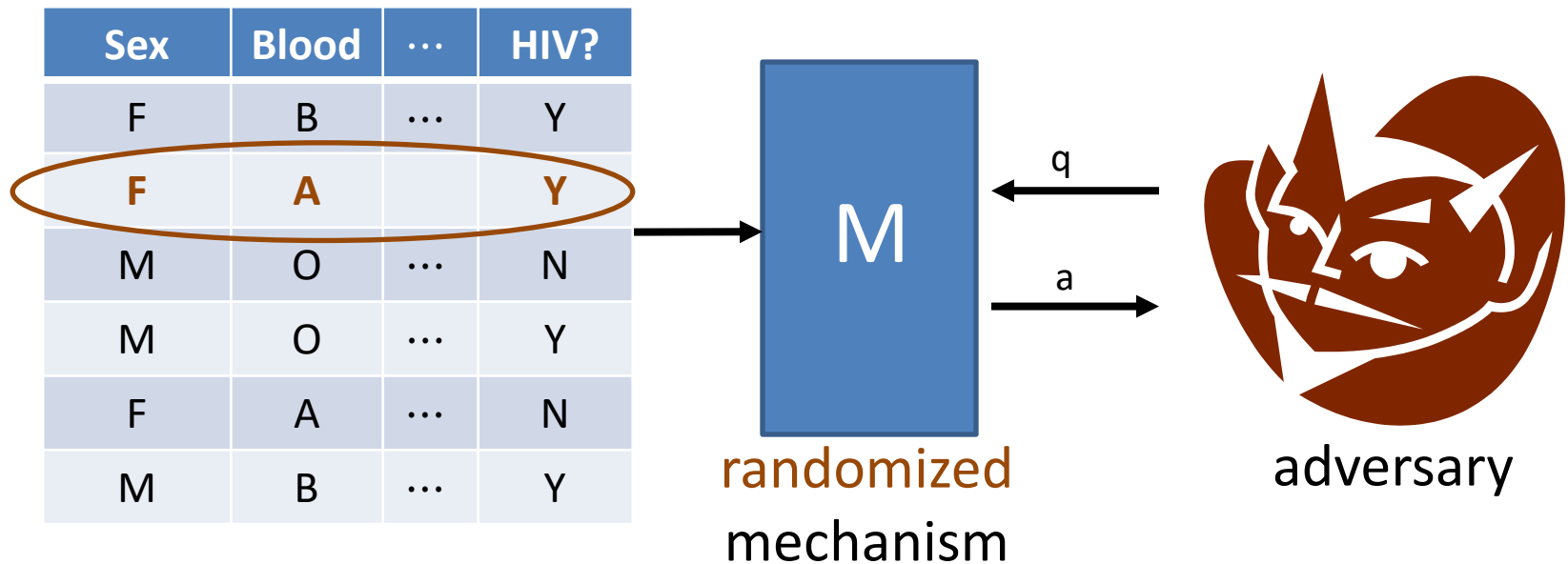


Requirement: for all x, x' differing on one row, and all q

$$\forall \text{ sets } T, \quad \Pr[M(x, q) \in T] \lesssim (1+\varepsilon) \cdot \Pr[M(x', q) \in T]$$

DP for one query/release

[Dwork-McSherry-Nissim-Smith '06]



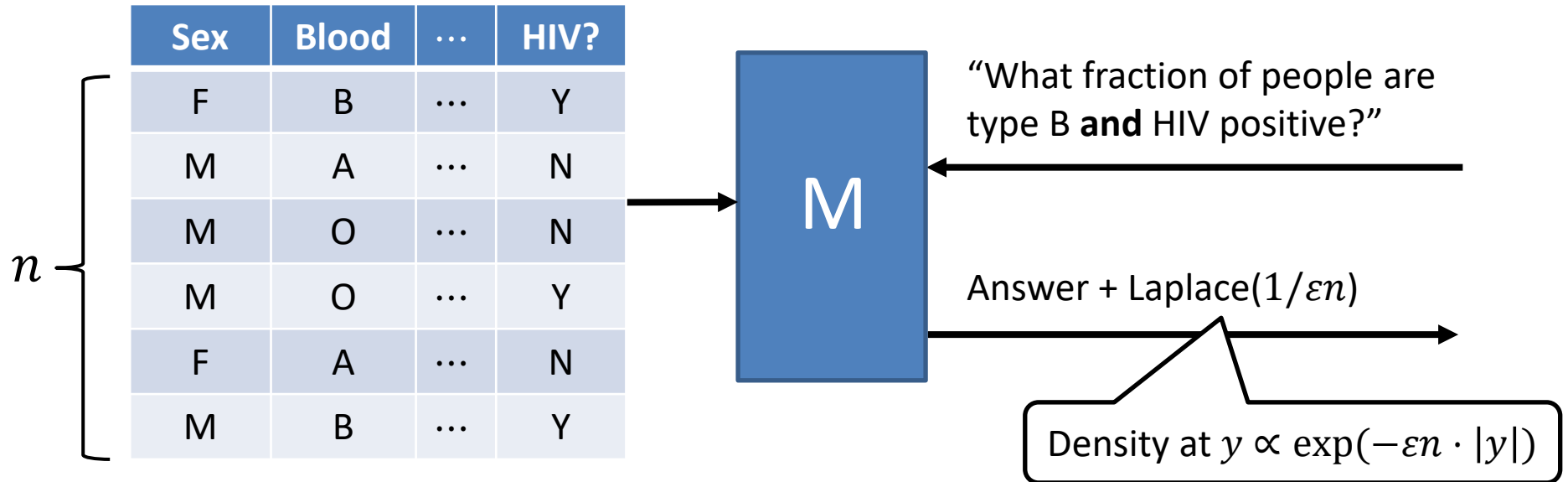
Def: M is ϵ -DP if for all x, x' differing on one row, and all q

$$\forall \text{ sets } T, \quad \Pr[M(x, q) \in T] \leq e^\epsilon \cdot \Pr[M(x', q) \in T]$$

(Probabilities are (only) over the randomness of M.)

The Laplace Mechanism

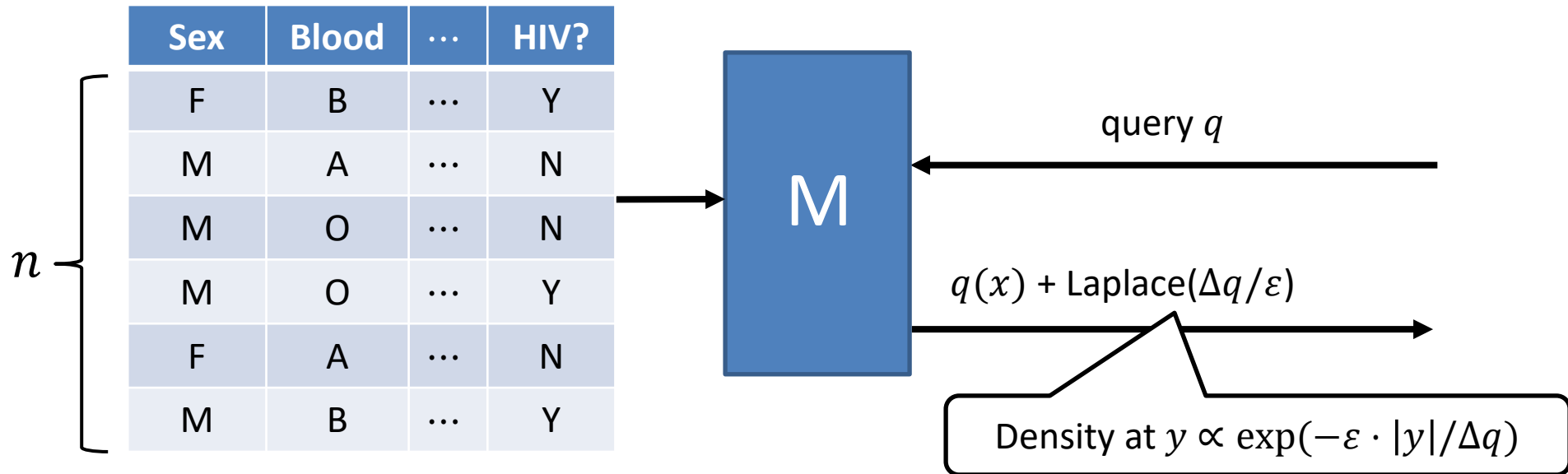
[Dwork-McSherry-Nissim-Smith '06]



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The Laplace Mechanism

[Dwork-McSherry-Nissim-Smith '06]



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The Laplace Mechanism

[Dwork-McSherry-Nissim-Smith '06]

- Let \mathcal{X} be a data universe, and \mathcal{X}^n a space of datasets.
 - This is the **Bounded DP** setting: n known and public.
- For $x, x' \in \mathcal{X}^n$, write $x \sim x'$ if x and x' differ on ≤ 1 row.

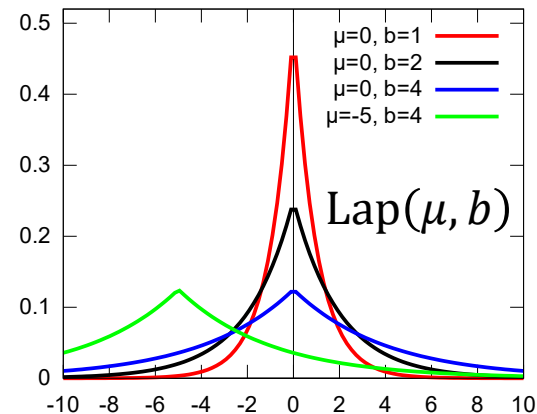
- For a query $q : \mathcal{X}^n \rightarrow \mathbb{R}$, the **global sensitivity** is

$$\Delta q = \text{GS}_q = \max_{x \sim x'} |q(x) - q(x')|.$$

- The **Laplace distribution** with scale s , $\text{Lap}(s)$:

- Has density function $f(y) = e^{-|y|/s} / 2s$.

- Mean 0, standard deviation $\sqrt{2} \cdot s$.



Theorem: $M(x, q) = q(x) + \text{Lap}(\Delta q/\epsilon)$ is ϵ -DP.

[By IkamusumeFan - Own work, CC BY-SA 4.0](#)

Calculating Global Sensitivity

1. $\mathcal{X} = \{0,1\}$, $q(x) = \sum_{i=1}^n x_i$, $\Delta q =$

2. $\mathcal{X} = \mathbb{R}$, $q(x) = \sum_{i=1}^n x_i$, $\Delta q =$

3. $\mathcal{X} = [0,1]$, $q(x) = \text{mean}(x_1, x_2, \dots, x_n)$, $\Delta q =$

4. $\mathcal{X} = [0,1]$, $q(x) = \text{median}(x_1, x_2, \dots, x_n)$, $\Delta q =$

5. $\mathcal{X} = [0,1]$, $q(x) = \text{variance}(x_1, x_2, \dots, x_n)$, $\Delta q =$

Q: for which of these queries is the Laplace Mechanism “useful”?

Properties of the Definition

- **Suffices to check pointwise:** M is ε -DP if and only if
$$\forall x \sim x' \forall q \forall y \Pr[M(x, q) = y] \leq e^\varepsilon \cdot \Pr[M(x', q) = y].$$
- **Preserved under post-processing:** If M is ε -DP and f is any function, then $M'(x, q) = f(M(x, q))$ is ε -DP.
- **(Basic) composition:** If M_i is ε_i -DP for $i = 1, \dots, k$, then
$$M'(x, (q_1, \dots, q_k)) = (M_1(x, q_1), \dots, M_k(x, q_k))$$
is $(\varepsilon_1 + \dots + \varepsilon_k)$ -DP
 - Use independent randomness for the k queries
 - Holds even if q_i 's are chosen adaptively

Interpreting the Definition

- Whatever an adversary learns about me, it could have learned from everyone else's data.
- Mechanism cannot leak "individual-specific" information.
- Above interpretations hold regardless of adversary's auxiliary information or computational power.
- **Protection against MIAs:** let $X = (X_1, \dots, X_n)$ be a r.v. distributed on \mathcal{X}^n and $X_{-i} = (X_1, \dots, X_{i-1}, \perp, X_{i+1}, \dots, X_n)$ be X with Alice's data removed. Then for every MIA A ,

$$\underbrace{\Pr[A(M(X)) = \text{"In"}]}_{\text{TPR on } X} \leq e^\epsilon \cdot \underbrace{\Pr[A(M(X_{-i})) = \text{"In"}]}_{\text{FPR on } X_{-i}}$$

Varying the Data Domain and Privacy Unit

- **Unbounded DP** (n not publicly known):
 - Datasets: **multisets** x from a data universe \mathcal{X}
 - Can represent as **histogram** $h_x: \mathcal{X} \rightarrow \mathbb{N}$, $h_x(i) = \#$ copies of i
 - Adjacency: $x \sim x'$ if $|x \Delta x'| \leq 1$ (add/remove 1 record)
 - Equivalently $\sum_{i \in \mathcal{X}} |h_x(i) - h_{x'}(i)| \leq 1$
 - **Social Networks:**
 - Datasets: graphs G
 - Adjacency: $G \sim G'$ if
 - differ by ≤ 1 edge (**edge privacy**), OR
 - differ by ≤ 1 node and incident edges (**node privacy**)
- Q:** which is better for privacy?

Real Numbers Aren't

[Mironov '12]

- Digital computers don't manipulate actual real numbers.
 - Floating-point implementations of the Laplace mechanism can have $M(x, q)$ and $M(x', q)$ disjoint \rightarrow privacy violation!
- **Solutions:**
 - Round outputs of M to a discrete value (with care).
 - Or use the **Geometric Mechanism**:
 - Ensure that $q(x)$ is always an integer multiple of g .
 - Define $M(x, q) = q(x) + g \cdot \text{Geo}(GS_q/g\varepsilon)$, where $\Pr[\text{Geo}(s) = k] \propto e^{-|k|/s}$ for $k \in \mathbb{Z}$.