

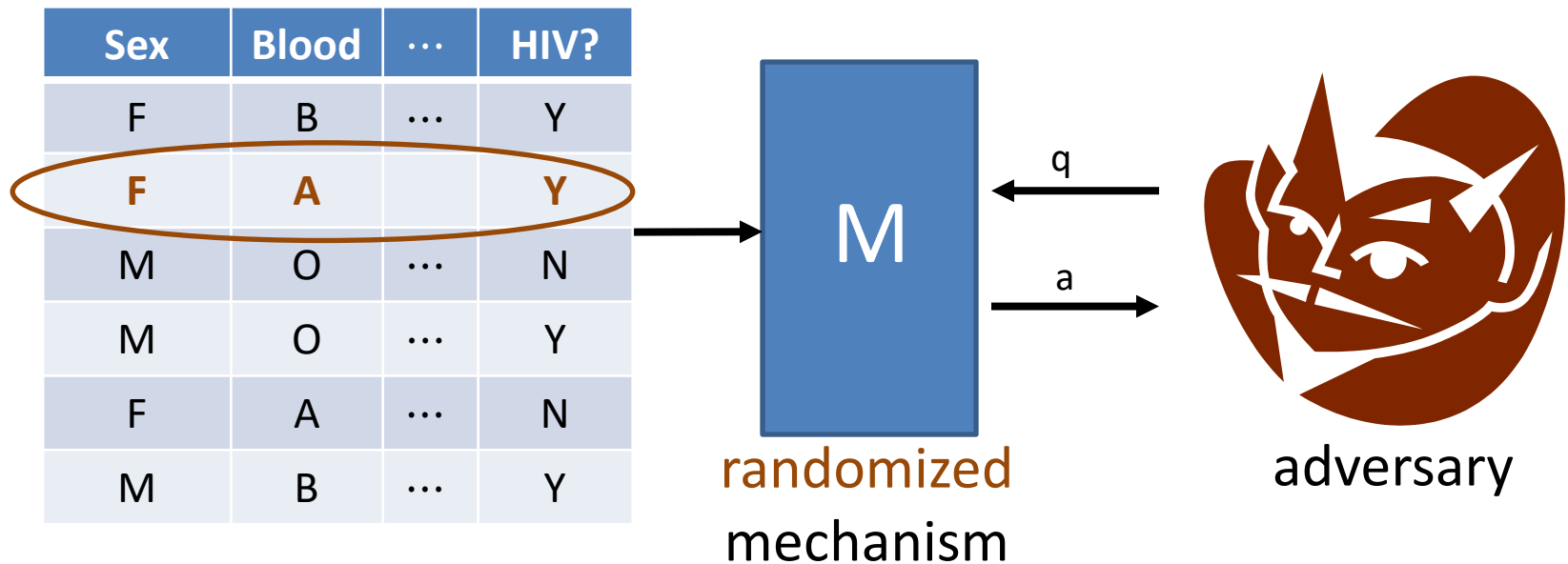
CS2080: Applied Privacy for Data Science **Introduction to Differential Privacy (cont.)**

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DP for one query/release

[Dwork-McSherry-Nissim-Smith '06]



Def: M is ϵ -DP if for all x, x' differing on one row, and all q

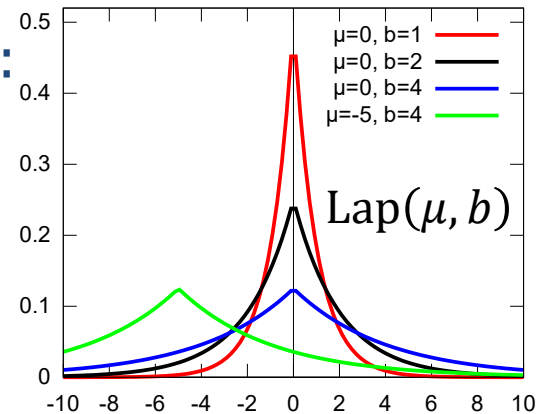
$$\forall \text{ sets } T, \quad \Pr[M(x, q) \in T] \leq e^\epsilon \cdot \Pr[M(x', q) \in T]$$

(Probabilities are (only) over the randomness of M.)

The Laplace Mechanism

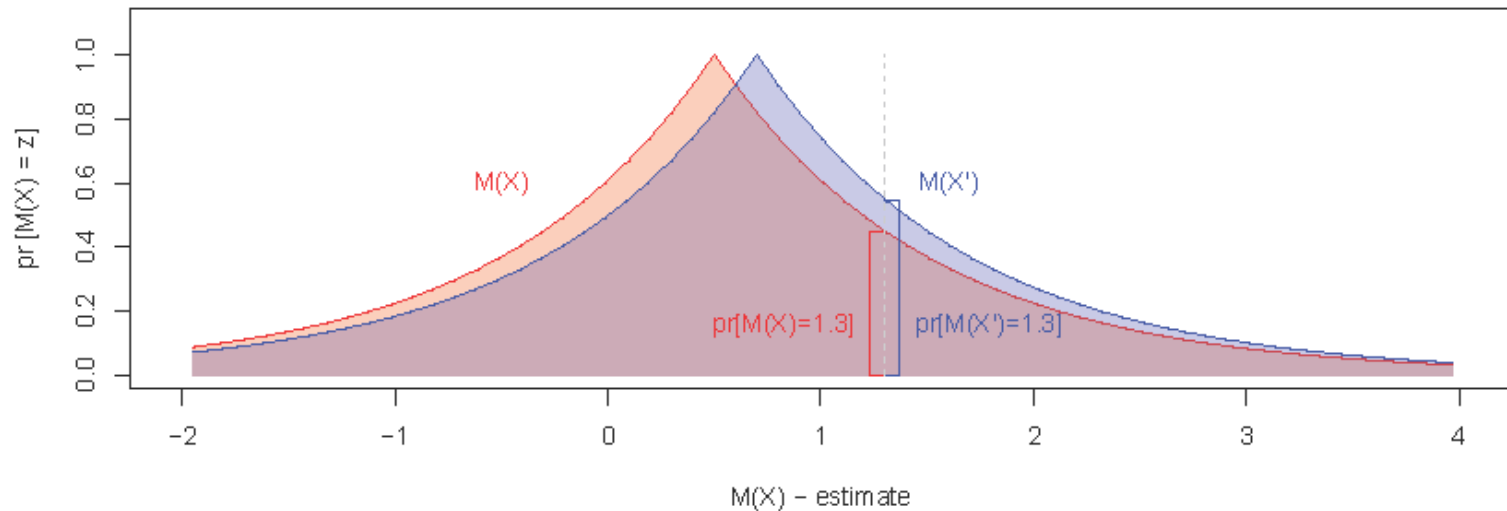
[Dwork-McSherry-Nissim-Smith '06]

- Let \mathcal{X} be a data universe, and \mathcal{X}^n a space of datasets.
 - This is the **Bounded DP** setting: n known and public.
- For $x, x' \in \mathcal{X}^n$, write $x \sim x'$ if x and x' differ on ≤ 1 row.
- For a query $q : \mathcal{X}^n \rightarrow \mathbb{R}$, the **global sensitivity** is
$$\Delta q = \text{GS}_q = \max_{x \sim x'} |q(x) - q(x')|.$$
- The **Laplace distribution** with scale b , $\text{Lap}(b)$:
 - Has density function $f(y) = e^{-|y|/b} / 2b$.
 - Mean 0, standard deviation $\sqrt{2} \cdot b$.



Theorem: $M(x, q) = q(x) + \text{Lap}(\Delta q/\epsilon)$ is ϵ -DP.

[By IkamusumeFan - Own work, CC BY-SA 4.0](#)



Two Laplace distributions, for two adjacent datasets x and x' . The definition of ϵ -differential privacy requires the ratio of $M(x)/M(x')$ is not greater than e^ϵ for all points along the x -axis. Thus for any realized output z (for example here, $z = 1.3$) we can not determine that x or x' were more likely to have produced z .

Calculating Global Sensitivity

1. $\mathcal{X} = \{0,1\}$, $q(x) = \sum_{i=1}^n x_i$, $\Delta q =$

2. $\mathcal{X} = \mathbb{R}$, $q(x) = \sum_{i=1}^n x_i$, $\Delta q =$

3. $\mathcal{X} = [0,1]$, $q(x) = \text{mean}(x_1, x_2, \dots, x_n)$, $\Delta q =$

4. $\mathcal{X} = [0,1]$, $q(x) = \text{median}(x_1, x_2, \dots, x_n)$, $\Delta q =$

5. $\mathcal{X} = [0,1]$, $q(x) = \text{variance}(x_1, x_2, \dots, x_n)$, $\Delta q =$

Q: for which of these queries is the Laplace Mechanism “useful”?

A:

Properties of the Definition

- **Suffices to check pointwise:** M is ε -DP if and only if
$$\forall x \sim x' \forall q \forall y \Pr[M(x, q) = y] \leq e^\varepsilon \cdot \Pr[M(x', q) = y].$$
- **Preserved under post-processing:** If M is ε -DP and f is any function, then $M'(x, q) = f(M(x, q))$ is ε -DP.
- **(Basic) composition:** If M_i is ε_i -DP for $i = 1, \dots, k$, then
$$M'(x, (q_1, \dots, q_k)) = (M_1(x, q_1), \dots, M_k(x, q_k))$$
is $(\varepsilon_1 + \dots + \varepsilon_k)$ -DP
 - Use independent randomness for the k queries
 - Holds even if q_i 's are chosen adaptively

Interpreting the Definition

- Whatever an adversary learns about me, it could have learned from everyone else's data.
- Mechanism cannot leak "individual-specific" information.
- Above interpretations hold regardless of adversary's auxiliary information or computational power.
- **Protection against MIAs:** let $X = (X_1, \dots, X_n)$ be a r.v. distributed on \mathcal{X}^n and $X_{-i} = (X_1, \dots, X_{i-1}, \perp, X_{i+1}, \dots, X_n)$ be X with Alice's data removed. Then for every MIA A ,

$$\Pr[A(M(X)) = \text{"In"}] \leq e^\epsilon \cdot \Pr[A(M(X_{-i})) = \text{"In"}]$$

Varying the Data Domain and Privacy Unit

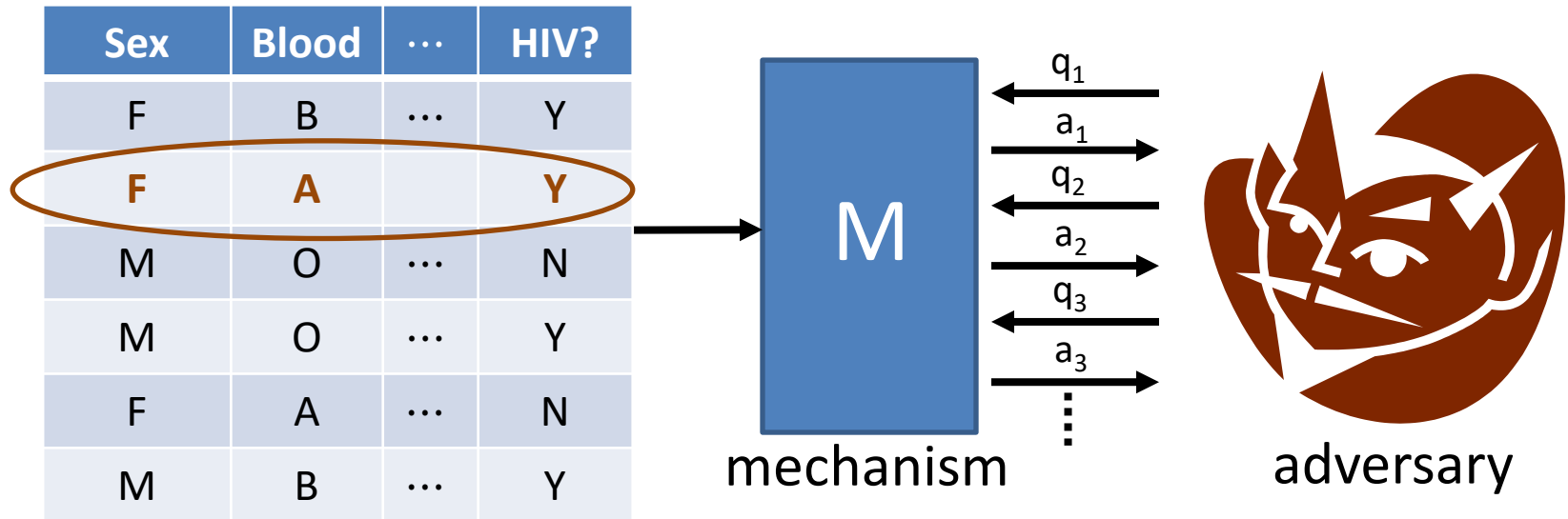
- **Unbounded DP** (n not publicly known):
 - Datasets: **multisets** x from a data universe \mathcal{X}
 - Can represent as **histogram** $h_x: \mathcal{X} \rightarrow \mathbb{N}$, $h_x(i) = \#$ copies of i
 - Adjacency: $x \sim x'$ if $|x \Delta x'| \leq 1$ (add/remove 1 record)
 - Equivalently $\sum_{i \in \mathcal{X}} |h_x(i) - h_{x'}(i)| \leq 1$
 - **Social Networks**:
 - Datasets: graphs G
 - Adjacency: $G \sim G'$ if
 - differ by ≤ 1 edge (**edge privacy**), OR
 - differ by ≤ 1 node and incident edges (**node privacy**)
- Q:** which is better for privacy?

Real Numbers Aren't

[Mironov '12]

- Digital computers don't manipulate actual real-numbers
 - Floating-point implementations of the Laplace Mechanism can have $M(x, q)$ and $M(x', q)$ disjoint \rightarrow privacy violation!
- Solutions:
 - Round outputs of M to a discrete number (with care).
 - Or use the **Geometric Mechanism**:
 - Ensure that $q(x)$ is always an integer multiple of γ .
 - Define $M(x, q) = q(x) + \gamma \cdot \text{Geo}(\Delta q / \gamma \epsilon)$,
where $\Pr[\text{Geo}(b) = k] \propto \exp(-|k|/b)$ for $k \in \mathbb{Z}$.

DP for Interactive Mechanisms

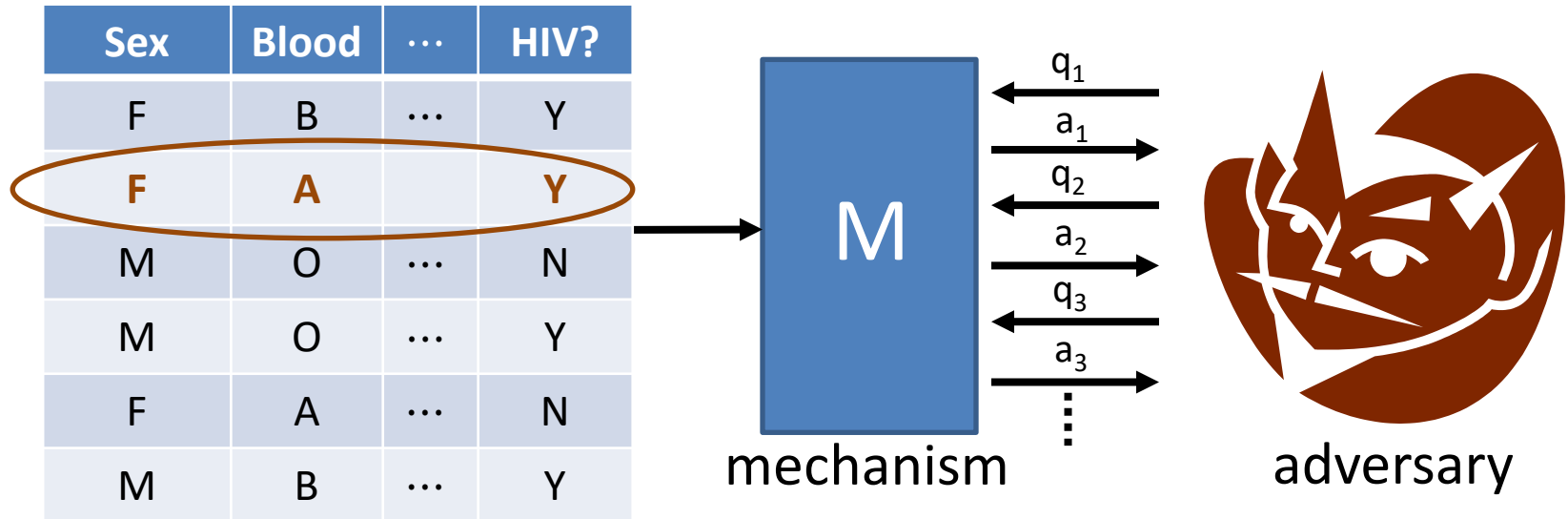


1st Attempt: for all $x \sim x'$, all q_1, \dots, q_t , all T

$$\Pr[M(x, q_1, \dots, q_t) \in T] \leq e^\varepsilon \cdot \Pr[M(x', q_1, \dots, q_t) \in T]$$

vectors of answers a_1, \dots, a_t

DP for Interactive Mechanisms



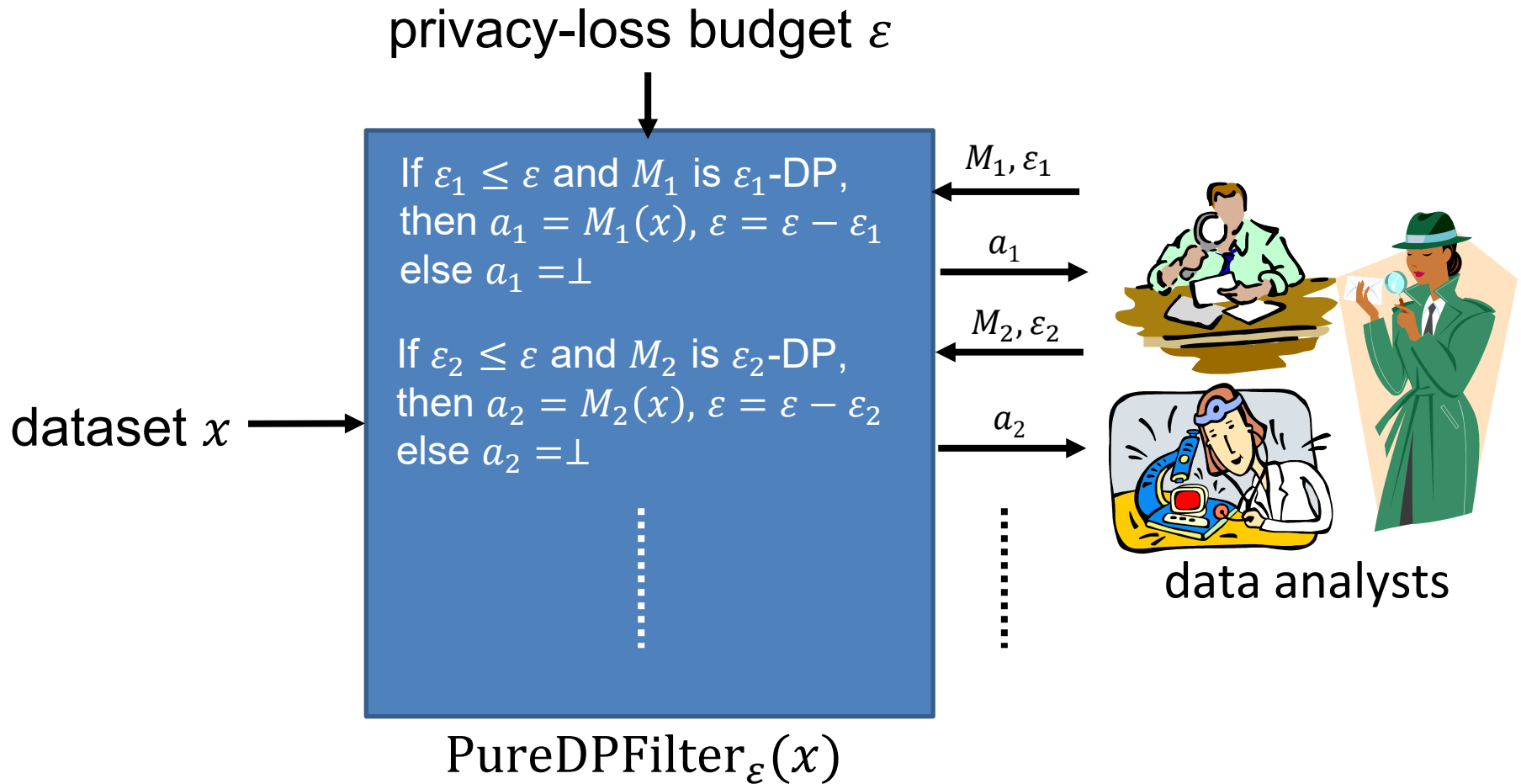
Better: for all $x \sim x'$, all adversarial strategies A

$$\underbrace{\text{View}_A(A \leftrightarrow M(x))}_{\text{Everything } A \text{ sees (its internal randomness \& query answers)}} \approx_{\varepsilon} \underbrace{\text{View}_A(A \leftrightarrow M(x'))}_{\text{Everything } A \text{ sees (its internal randomness \& query answers)}}$$

Everything A sees (its internal randomness & query answers)

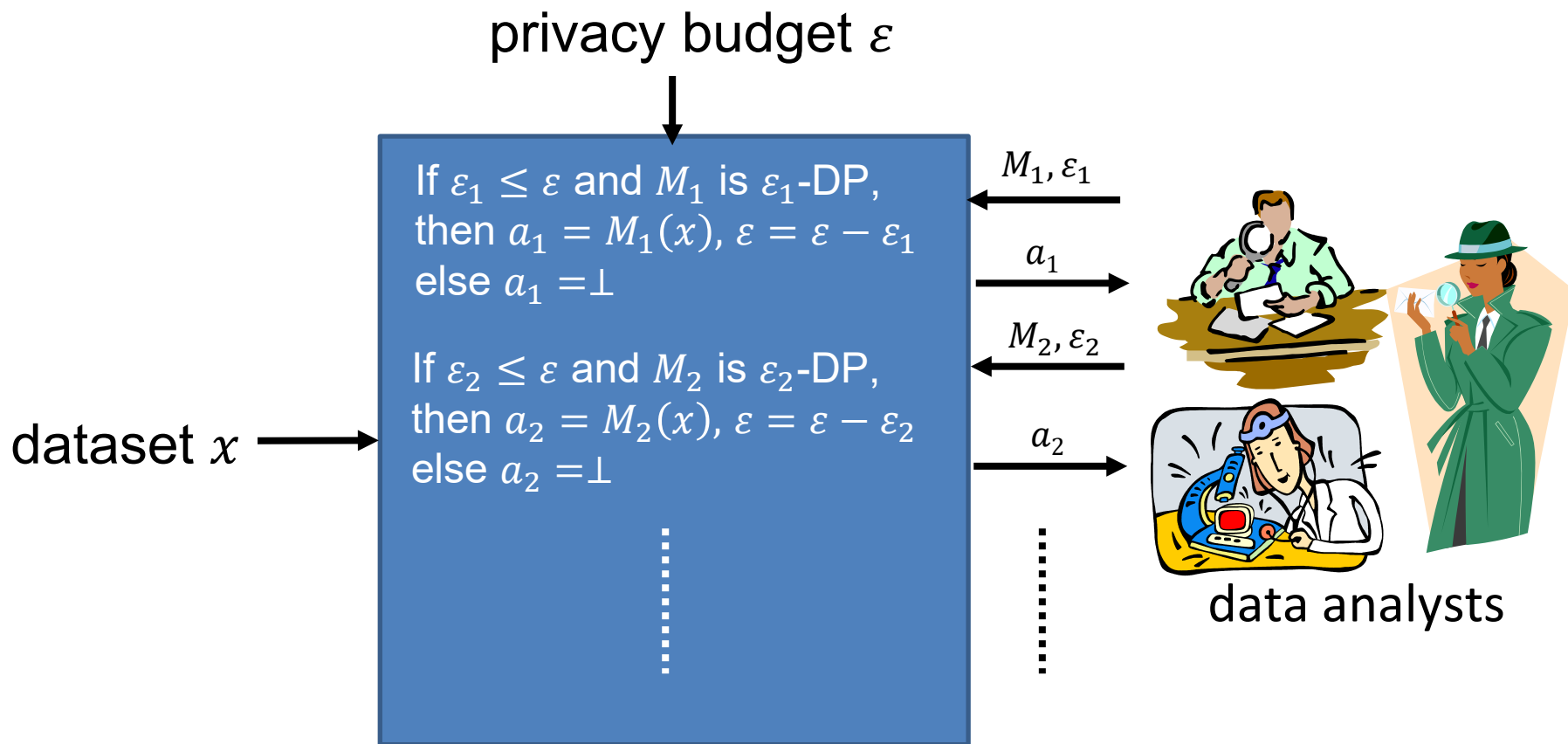
Equivalently: $\forall A \Pr[A \text{ outputs "In" after interacting w/} M(x)] \leq e^{\varepsilon} \cdot \Pr[A \text{ outputs "In" after interacting w/} M(x')]$

Composition as an Interactive Mechanism



Theorem: PureDPFilter $_{\varepsilon}$ is an ε -DP interactive mechanism.

Privacy Budgeting



- To answer k queries, can set each $\varepsilon_i = \varepsilon/k$.
- More queries \Rightarrow smaller $\varepsilon_i \Rightarrow$ less accuracy per query.
- Some tradeoff #queries vs. accuracy necessary. (Q: why?)

Composition for Algorithm Design

Composition and post-processing allow designing more complex differentially private algorithms from simpler ones.

Example: The “Statistical Query Model” for ML

- Many ML algorithms (e.g. stochastic gradient descent) can be described as sequence of low-sensitivity queries (e.g. averages) over the dataset, and can tolerate noisy answers to the queries.
- Can answer each query by adding Laplace noise.
- By composition and post-processing, trained model is DP and safe to output.

Group Privacy & Setting ϵ

- **Proposition:** If M is ϵ -DP for individuals, then it is $k\epsilon$ -DP for groups of k individuals. That is, if x and x' differ on at most k individuals, then

$$\forall T \Pr[M(x) \in T] \leq e^{k\epsilon} \cdot \Pr[M(x') \in T]$$

- **Q:** what are examples of “groups” for which this is useful?
- **Consequence:** need $n \gg 1/\epsilon$ for any reasonable utility.
- Typical recommendation for a “good” privacy guarantee: $.01 \leq \epsilon \leq 1$.